

## HW 4 Computational Physics

September 13, 2005

Due September 20

It is good practice to use high-quality existing routines rather than writing your own. Here you will compare your `rk4` function with `scipy`'s ordinary differential equation solver `odeint`, with particular attention to the step size `tau` and the run time.

1. Consider the stiff set of ordinary differential equations:

$$\frac{dy}{dt} = -ay, \text{ where } y(t) = \begin{pmatrix} y_1(t) \\ y_2(t) \end{pmatrix}, \quad a = \begin{pmatrix} -9998 & -19998 \\ 9999 & 19999 \end{pmatrix},$$

with initial conditions  $y_1(0) = 2$ ,  $y_2(0) = -1$ . Show that this is solved exactly by

$$y(t) = \begin{pmatrix} 2e^{-t} \\ -e^{-t} \end{pmatrix}$$

by plugging this into the differential equation.

2. Numerically solve for  $y(t)$  for  $t = 0$  to  $t = 6$  using your Runge-Kutta function `rk4` from the last homework. Use a step size  $\tau = 0.0001$ . Print the time taken by the call to `rk4` and print the final value of  $y$  at  $t = 6$ . Plot the analytic and numerical  $y_1(t)$  and  $y_2(t)$  vs.  $t$  together on one graph. Snippet:

```
def stiff(yn,tn) :
    # RHS of the first-order coupled ODE's.
    ...
    return rhs
def rk4(f,y0,t):
    ...
    # Main code
    y0=array([2.,-1.])
    tfinal, tau = 6., 0.0001
    t = arange(0,tfinal+tau,tau)
    start = time.clock()
    y = rk4(stiff,y0,t)
    finish = time.clock()
    elapsed = finish - start
```

3. Repeat using a step size  $\tau = 0.01$ . Start at  $t = 0$  and calculate for ten or twenty time steps, printing the calculated values, until your numerical answer goes bad.
4. Find the eigenvalues of  $a$  and explain why (2) works and (3) does not.
5. Solve for times  $0 \leq t \leq 6$  using `odeint` and a step size  $\tau = 0.01$ . To learn how to use `odeint` try

```
from scipy.integrate import odeint
help(odeint)
```

In your code print the time for the call to `odeint` and plot your solution and the analytic solution together as in (2). Do you see the benefit of using an algorithm such as `odeint` designed to handle stiff problems? Discuss.