

REVIEW LECTUREBEFORE SPRING BREAK

MAGNETIC FIELD

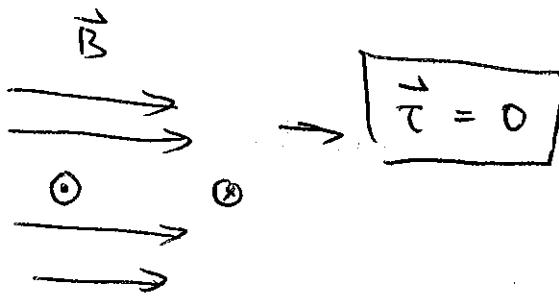
$$\vec{B} \Rightarrow \vec{F} = q(\vec{v} \times \vec{B}) + q\vec{E}$$

TORQUE ON CURRENT LOOP



$$\vec{N} = I \vec{A}$$

$$\vec{\tau} = \vec{\mu} \times \vec{B}$$

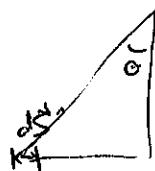
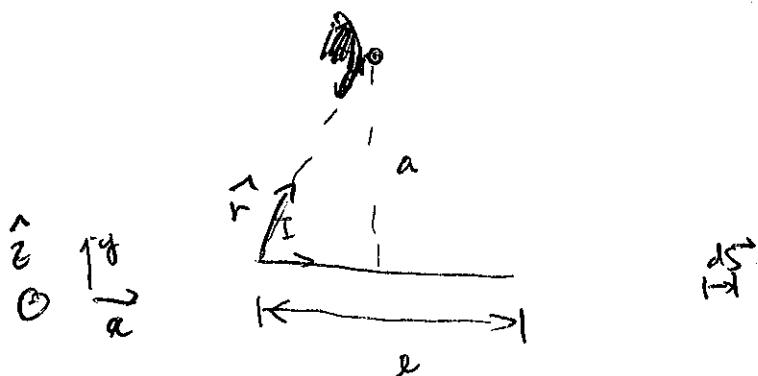


$$\boxed{\vec{\tau} = 0}$$

SOURCES OF MAGNETIC FIELD

Biot - Savart Law

$$d\vec{B} = \frac{\mu_0}{4\pi} \frac{I d\vec{s} \times \hat{r}}{r^2}$$



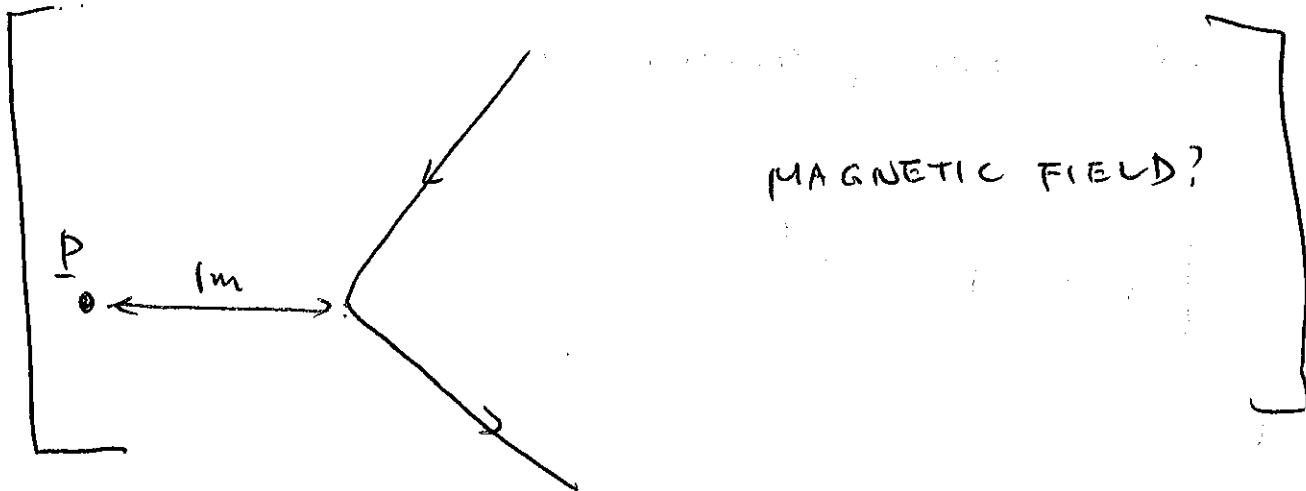
$$d\vec{s} \times \hat{r} = \sin(90^\circ - \theta) dx \hat{r} = -\cos \theta dx \hat{z}$$

$$d\vec{B} = \frac{\mu_0 I}{4\pi r^2} dx \cos \theta \hat{z}$$

$$r = \frac{a}{\cos \theta}$$

~~$$\vec{B} = \frac{\mu_0 I}{4\pi} \int_{-a}^a \frac{dx \cos \theta \hat{z}}{x^2}$$~~

$$x = -a \tan \theta \quad \therefore \quad dx = -a \sec^2 \theta d\theta$$



$$d\vec{B} = \frac{\mu_0 I}{4\pi} \frac{-d\theta}{\cos\theta} \sin\theta \cos\theta \cdot \frac{\cos^2\theta}{a}$$

$$= -\frac{\mu_0 I}{4\pi} \cos\theta d\theta$$

AMPERE'S LAW

$$\int \vec{B} \cdot d\vec{s} = \mu_0 I$$

FORCES ON CURRENT CARRYING WIRE

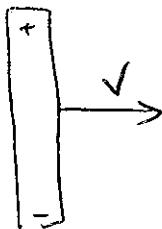
$$\vec{F} = I \vec{C} \times \vec{B}$$

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FARADAY'S LAW

$$\mathcal{E} = - \frac{d\Phi_B}{dt}$$

MOTIONAL EMF

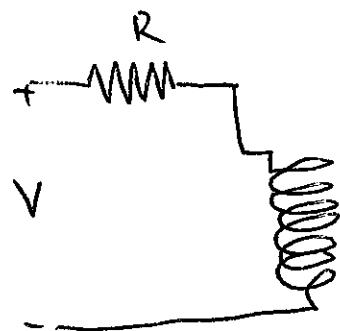


INDUCED EMF AND ELECTRIC FIELDS

$$\oint \vec{E} \cdot d\vec{s} = - \frac{d\Phi_B}{dt}$$

INDUCTANCE

$$\mathcal{E}_L = - L \frac{dI}{dt}$$



$$V = IR + \mathcal{E}_L$$

$$=$$

EMF OPPOSES THE APPLIED
VOLTAGE

For a coil

$$\mathcal{E} = -N \frac{d\Phi}{dt}$$



$$L = \frac{\mu N^2 A}{l}$$

RL CIRCUIT

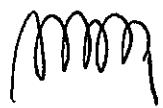
ENERGY IN \vec{B} FIELD

$\rightarrow U = \frac{1}{2} L I^2$

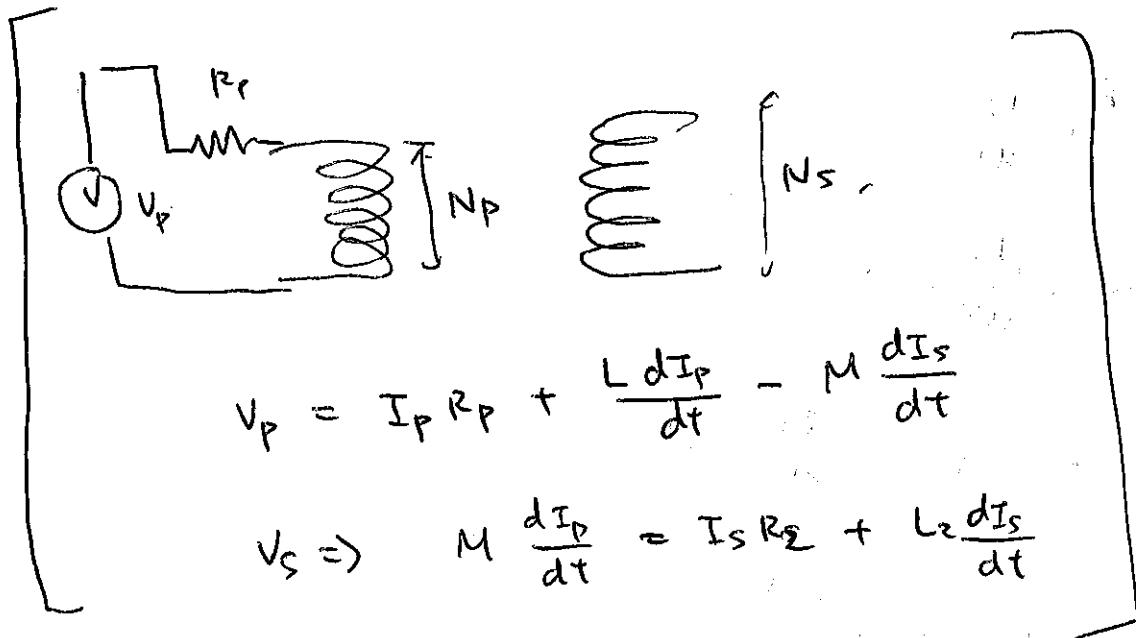
$\rightarrow M_B = \frac{U}{J} = \frac{B^2}{2 \mu_0}$

MUTUAL INDUCTANCE

$$(M_{12} = \frac{N_2 \Phi_{12}}{I_1})$$



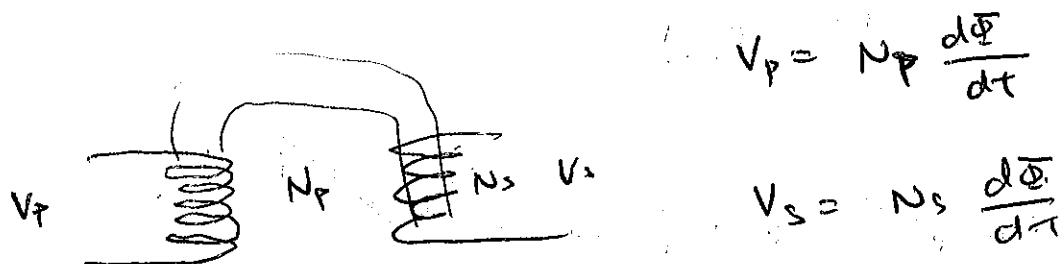
$$\mathcal{E}_2 = -M_{12} \frac{dI_1}{dt}$$



$$V_P = I_P R_P + L \frac{dI_P}{dt} = M \frac{dI_S}{dt}$$

$$V_S \Rightarrow M \frac{dI_P}{dt} = I_S R_S + L_S \frac{dI_S}{dt}$$

CAMPIONATRICE

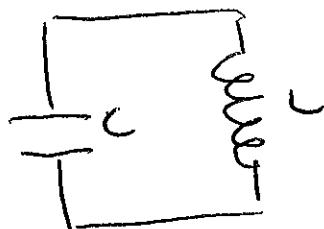


$$V_P = N_P \frac{d\Phi}{dt}$$

$$V_S = N_S \frac{d\Phi}{dt}$$

$$\frac{V_P}{V_S} = \frac{N_P}{N_S}$$

LC CIRCUIT



$$-\frac{Q}{C} - L \frac{dI}{dt} = 0$$

$$\frac{Q}{C} + L \frac{dI}{dt} = 0$$

$$\frac{Q}{C} \cancel{-t} + L \frac{d^2Q}{dt^2} = 0$$

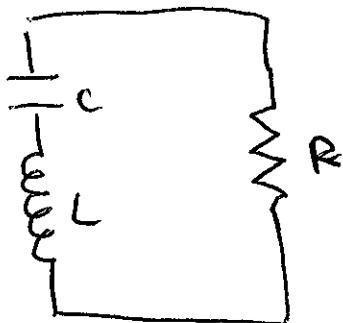
$$Q = Q_0 e^{i\omega t}$$

$$\omega = \frac{1}{\sqrt{LC}}$$

$$\cancel{\frac{Q_0}{C} e^{i\omega t}} + (-\omega^2) \cancel{Q_0 e^{i\omega t}} = 0$$

$$\frac{1}{C} = \omega^2 L$$

$$\boxed{\omega^2 = \frac{1}{LC}}$$

RLC CIRCUIT

$$-IR - \frac{Q}{C} - L \frac{dI}{dt} = 0$$

$$IR + \frac{Q}{C} + L \frac{dI}{dt}$$

$$\frac{Q}{C} + I \frac{dQ}{dt} + L \frac{d^2Q}{dt^2} = 0$$

$$Q = Q_0 e^{int}$$

$$\frac{\frac{dQ}{dt}}{C} + R \omega Q_0 e^{int} + L \omega (-\omega^2) e^{int} = 0$$

$$\frac{1}{C} + i\omega R + -\omega^2 = 0$$

$$\omega =$$

$$\omega^2 - i\omega R \cancel{-} \frac{1}{LC} = 0 \quad (-i)^2 = -1$$

$$\omega = \frac{iR}{L} \pm \sqrt{+\frac{\omega^2}{L^2} + \frac{1}{LC}}$$

$$e^{-\frac{R}{2L}t} e^{i \sqrt{\frac{1}{LC} - \frac{\omega^2}{4L^2}} t}$$

✓

